

ICCAS 2024 Session Timetable

Jeju Shinhwa World Landing Convention Center								
	Room 1 (Landing Ballroom)	Room 2 (Halla Room A+B)	Room 3 (Halla Room C)	Room 4	Room 5	Room 6	Room 7	Room 8
<b>October 29 (Tuesday)</b>								
10:00-13:00	<b>Tutorial 1</b>	<b>Workshop</b>						
	A Tutorial on Data-Enabled Predictive Control (DeePC)							
13:00-14:00	<b>Break</b>							
14:00-17:00	<b>Tutorial 2</b>	MATLAB Educator Workshop: Teaching Computation and Design (11:30-17:50)		<b>Workshop</b>				
	Feedback integrators: A new method for structure-preserving numerical integration and controller design for dynamical systems on manifolds							
14:00-17:00			The 5th Smart Power Platform Workshop (in Korean) (13:00-14:30)					
17:00-18:00	<b>Poster Session (TuPo)</b>							
18:20-19:20	<b>Welcome Reception - Landing Ballroom</b>							
<b>October 30 (Wednesday)</b>								
09:00-10:30		<b>WeA2</b>	<b>WeA3</b>	<b>WeA4</b>	<b>WeA5</b>	<b>WeA6</b>	<b>WeA7</b>	<b>WeA8</b>
		Award Session 1	Industrial Applications of Control 1	Autonomous Vehicle Systems 1	Biomechanics and Biomedical Systems	Daejeon-Chungcheong Dissemination Session	Deep Learning and Machine Vision Applications 1	Multi-Agent Systems
10:30-10:50	<b>Break</b>							
10:50-11:40	<b>Opening Ceremony &amp; Plenary Lecture I (Prof. Florian Dorfler, Switzerland) - Landing Ballroom</b>							
11:40-13:00	<b>Lunch</b>							
13:00-14:30		<b>WeB2</b>	<b>WeB3</b>	<b>WeB4</b>	<b>WeB5</b>	<b>WeB6</b>	<b>WeB7</b>	<b>WeB8</b>
		Koh Young AI Competition	Industrial Applications of Control 2	Autonomous Vehicle Systems 2	Medical and Rehabilitation Robot	ECT-ICROS Joint Organized Session on Advanced Control Designs and Applications	Deep Learning and Machine Vision Applications 2	China-Korea-Japan Joint Session on Advanced Control of Network and Dynamic Systems 1
14:30-14:50	<b>Break</b>							
14:50-15:50	<b>Plenary Lecture II (Prof. Yoshito Ohta, Japan) - Landing Ballroom</b>							
15:50-16:10	<b>Break</b>							
16:10-17:40			<b>WeC3</b>	<b>WeC4</b>	<b>WeC5</b>	<b>WeC6</b>	<b>WeC7</b>	<b>WeC8</b>
			Control Applications 1	SICE-ICROS Joint Organized Session : Robot Technology and Its Application	Localization and Mapping	Computer Vision	Sensor and Signal Processing 1	China-Korea-Japan Joint Session on Advanced Control of Network and Dynamic Systems 2
<b>October 31 (Thursday)</b>								
09:00-10:30		<b>ThA2</b>	<b>ThA3</b>	<b>ThA4</b>	<b>ThA5</b>	<b>ThA6</b>	<b>ThA7</b>	<b>ThA8</b>
		Award Session 2	Control Applications 2	ICROS Technical Committee on Control Theory 1	Navigation 1	Fault Detection	Sensor and Signal Processing 2	China-Korea-Japan Joint Session on Advanced Control of Network and Dynamic Systems 3
10:30-10:50	<b>Break</b>							
10:50-11:40	<b>Plenary Lecture III (Prof. Jan Peters, Germany) - Landing Ballroom</b>							
11:40-13:00	<b>Lunch</b>							
13:00-14:30	<b>ThB1</b>	<b>ThB2</b>	<b>ThB3</b>	<b>ThB4</b>	<b>ThB5</b>	<b>ThB6</b>	<b>ThB7</b>	<b>ThB8</b>
	Frontiers Session	Process Control, Estimation, and Modeling	Control Theory and Applications 1	ICROS Technical Committee on Control Theory 2	Navigation 2	Optimization and Optimal Control	Reinforcement Learning	Robot Mechanism and Control
14:30-14:50	<b>Break</b>							
14:50-15:50	<b>Plenary Lecture IV (Prof. Dongil "Dan" Cho, Korea) - Landing Ballroom</b>							
15:50-16:10	<b>Break</b>							
16:10-17:10	<b>Poster Session (ThPo)</b>							
17:40-19:40	<b>Banquet - Landing Ballroom</b>							
<b>November 1 (Friday)</b>								
09:00-10:30		<b>FrA2</b>	<b>FrA3</b>	<b>FrA4</b>	<b>FrA5</b>	<b>FrA6</b>	<b>FrA7</b>	<b>FrA8</b>
		Dynamics in Signal Processing and Control: Application	Control Theory and Applications 2	Deep Learning Applications	Medical Robot and Simulation	Robotic Applications 1	Human-Robot Interaction	Sliding Mode Control
10:30-10:50	<b>Break</b>							
10:50-11:40	<b>Plenary Lecture V (Prof. Lei Guo, China) - Landing Ballroom</b>							
11:40-13:00	<b>Lunch</b>							
13:00-14:30		<b>FrB2</b>	<b>FrB3</b>	<b>FrB4</b>		<b>FrB6</b>	<b>FrB7</b>	
		Dynamics in Signal Processing and Control: Theory	Control Theory and Applications 3	Computer Vision for Robots		Robotic Applications 2	Agricultural and Construction Robotics	
14:30-14:50	<b>Break</b>							
14:50-15:50	<b>Poster Session (FrPo)</b>							